Image Processing & Pattern

E1425

Lecture 5

Two-Dimensional Discrete Fourier Transform

INSTRUCTOR

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Contents

➢ Summary of FT, FS, DTFT/DSFT, DFS, DFT and FFT

Fourier Transform (FT):

$x(t)$ (continuous) ⇄ $X(\Omega)$ (continuous)

$$X(\Omega) = \int_{-\infty}^{\infty} x(t) e^{-j\Omega t} dt$$

$$x(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} X(\Omega) e^{j\Omega t} d\Omega$$

Fourier Series (FS):

$x(t)$ (continuous, periodic) ⇄ X_m (discrete)

$$X_m = \frac{1}{T} \int_{-T/2}^{T/2} x(t) e^{-jm\Omega_0 t} dt \qquad \Omega_0 = \frac{2\pi}{T}$$

$$x(t) = \sum_{m=-\infty}^{\infty} X_m e^{jm\Omega_0 t}$$

Discrete Time/Space Fourier Transform (DTFT/DSFT):

$x(n)$ (discrete) ⇄ $X(\omega)$ (continuous, periodic)

$$X(\omega) = \sum_{n=-\infty}^{\infty} x(n) e^{-j\omega n}$$

$$x(n) = \frac{1}{2\pi} \int_{-\pi}^{\pi} X(\omega) e^{j\omega n} d\omega$$

➢ Summary of FT, FS, DTFT/DSFT, DFS, DFT and FFT

Discrete Fourier Series (DFS):

$\tilde{x}(n)$ (discrete, periodic) ⇄ $\tilde{X}_m$ (discrete, periodic)

$$\tilde{X}_m = \sum_{n=0}^{N-1} \tilde{x}(n) e^{-j2\pi nm/N}$$

$$\tilde{x}(n) = \frac{1}{N} \sum_{m=0}^{N-1} \tilde{X}_m e^{j2\pi mn/N}$$

Discrete Fourier Transform (DFT):

$x(n)$ (discrete, finite) ⇄ $X(m)$ (discrete, finite)

$$X(m) = \sum_{n=0}^{N-1} x(n) e^{-j2\pi nm/N}$$

$$x(n) = \frac{1}{N} \sum_{m=0}^{N-1} X(m) e^{j2\pi mn/N}$$

Fast Fourier Transform (FFT): Fast algorithm for computing DFT

Two-Dimensional Discrete Fourier Transform (2D-DFT)

➢ 2D DFT and Inverse DFT (IDFT)

$$F(u, v) = \frac{1}{MN} \sum_{x=0}^{M-1} \sum_{y=0}^{N-1} f(x, y) e^{-j2\pi(ux/M + vy/N)}$$

$$f(x, y) \rightleftarrows F(u, v)$$

$$f(x, y) = \sum_{u=0}^{M-1} \sum_{v=0}^{N-1} F(u, v) e^{j2\pi(ux/M + vy/N)}$$

M, *N*: image size

x, *y*: image pixel position

u, *v*: spatial frequency

often used short notation:

$$W_N = e^{-j2\pi/N}$$

➢ The Meaning of DFT and Spatial Frequencies

- **Important Concept**

  Any signal can be represented as a linear combination of a set of basic components

$$f(x, y) = \sum_{u=0}^{M-1} \sum_{v=0}^{N-1} F(u, v) e^{j2\pi(ux/M + vy/N)}$$

  - Fourier components: sinusoidal patterns
  - Fourier coefficients: weighting factors assigned to the Fourier components

- Spatial frequency: The frequency of Fourier component
- Not to confused with electromagnetic frequencies (e.g., the frequencies associated with light colors)

➢ Real Part, Imaginary Part, Magnitude, Phase, Spectrum

Real part:	$R = \text{Real}(F)$
Imaginary part:	$I = \text{Imag}(F)$
Magnitude-phase representation:	$F(u, v) = \lvert F(u, v)\rvert e^{-j\phi(u,v)}$
Magnitude (spectrum):	$\lvert F(u, v)\rvert = \left[R^2(u, v) + I^2(u, v)\right]^{1/2}$
Phase (spectrum):	$\phi(u, v) = \tan^{-1}\left[\dfrac{I(u, v)}{R(u, v)}\right]$
Power Spectrum:	$P(u, v) = \lvert F(u, v)\rvert^2$

➢ 2D DFT Properties

Mean of image/ DC component: $\bar{f}(x, y) = F(0, 0) = \frac{1}{MN} \sum_{x=0}^{M-1} \sum_{y=0}^{N-1} f(x, y)$

Highest frequency component: $f(x, y)(-1)^{x+y} \Leftrightarrow F(u - M/2, v - N/2)$

"Half-shifted" Image: $f(x - M/2, y - N/2) \Leftrightarrow F(u, v)(-1)^{u+v}$

Conjugate Symmetry: $F(u, v) = F^*(-u, -v)$

Magnitude Symmetry: $|F(u, v)| = |F(-u, -v)|$

➢ 2D DFT Properties

Spatial domain differentiation: $\frac{\partial^n f(x,y)}{\partial x^n} \Leftrightarrow (ju)^n F(u,v)$

Frequency domain differentiation: $(-jx)^n f(x,y) \Leftrightarrow \frac{\partial^n F(u,v)}{\partial u^n}$

Distribution law: $\Im[f_1(x,y) + f_2(x,y)] = \Im[f_1(x,y)] + \Im[f_2(x,y)]$

Laplacian: $\nabla^2 f(x,y) \Leftrightarrow -(u^2 + v^2)F(u,v)$

Spatial domain Periodicity: $f(x,y) = f(x+M,y) = f(x,y+N) = f(x+M,y+N)$

Frequency domain periodicity: $F(u,v) = F(u+M,v) = F(u,v+N) = F(u+M,v+N)$

➢ Computation of 2D-DFT

Fourier transform matrices: remember $W_N = e^{-j2\pi/N}$

$$F_N = \begin{bmatrix} 1 & 1 & 1 & \cdots & 1 \\ 1 & W_N & W_N^2 & \cdots & W_N^{N-1} \\ \vdots & \vdots & \vdots & & \vdots \\ 1 & W_N^{N-1} & W_N^{2(N-1)} & \cdots & W_N^{(N-1)^2} \end{bmatrix} \qquad F_N^* = \begin{bmatrix} 1 & 1 & 1 & \cdots & 1 \\ 1 & W_N^{-1} & W_N^{-2} & \cdots & W_N^{1-N} \\ \vdots & \vdots & \vdots & & \vdots \\ 1 & W_N^{1-N} & W_N^{2(1-N)} & \cdots & W_N^{-(N-1)^2} \end{bmatrix}$$

relationship: $F_N^{-1} = \frac{1}{N} F_N^*$

In particular, for $N = 4$:

$$F_4 = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & -j & -1 & j \\ 1 & -1 & 1 & -1 \\ 1 & j & -1 & -j \end{bmatrix} \qquad F_4^* = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & j & -1 & -j \\ 1 & -1 & 1 & -1 \\ 1 & -j & -1 & j \end{bmatrix}$$

➢ Computation of 2D-DFT

- To compute the 1D-DFT of a 1D signal **x** (as a vector):

$$\tilde{\mathrm{x}} = \mathrm{F}_N \mathrm{x}$$

To compute the inverse 1D-DFT:

$$\mathrm{x} = \frac{1}{N} \mathrm{F}_N^* \tilde{\mathrm{x}}$$

- To compute the 2D-DFT of an image **X** (as a matrix):

$$\widetilde{\mathrm{X}} = \mathrm{F}_N \mathrm{X} \mathrm{F}_N$$

To compute the inverse 2D-DFT:

$$\mathrm{X} = \frac{1}{N^2} \mathrm{F}_N^* \widetilde{\mathrm{X}} \mathrm{F}_N^*$$

➢ Computation of 2D-DFT: Example

- A 4x4 image

$$X = \begin{bmatrix} 1 & 3 & 6 & 8 \\ 9 & 8 & 8 & 2 \\ 5 & 4 & 2 & 3 \\ 6 & 6 & 3 & 3 \end{bmatrix}$$

- Compute its 2D-DFT:

$$\tilde{X} = F_4 X F_4 = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & -j & -1 & j \\ 1 & -1 & 1 & -1 \\ 1 & j & -1 & -j \end{bmatrix} \begin{bmatrix} 1 & 3 & 6 & 8 \\ 9 & 8 & 8 & 2 \\ 5 & 4 & 2 & 3 \\ 6 & 6 & 3 & 3 \end{bmatrix} \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & -j & -1 & j \\ 1 & -1 & 1 & -1 \\ 1 & j & -1 & -j \end{bmatrix}$$

MATLAB function: *fft2*

$$= \begin{bmatrix} 21 & 21 & 19 & 16 \\ -4-3j & -1-2j & 4-5j & 5+j \\ -9 & -7 & -3 & 6 \\ -4+3j & -1+2j & 4+5j & 5-j \end{bmatrix} \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & -j & -1 & j \\ 1 & -1 & 1 & -1 \\ 1 & j & -1 & -j \end{bmatrix}$$

lowest frequency component

$$= \begin{bmatrix} 77 & 2-5j & 3 & 2+5j \\ 4-9j & -11+8j & -4-7j & -5-4j \\ -13 & -6+13j & -11 & -6-13j \\ 4+9j & -5+4j & -4+7j & -11-8j \end{bmatrix}$$

highest frequency component

➢ Computation of 2D-DFT: Example

$$\tilde{X} = \begin{bmatrix} 77 & 2-5j & 3 & 2+5j \\ 4-9j & -11+8j & -4-7j & -5-4j \\ -13 & -6+13j & -11 & -6-13j \\ 4+9j & -5+4j & -4+7j & -11-8j \end{bmatrix}$$

Real part:

$$\tilde{X}_{real} = \begin{bmatrix} 77 & 2 & 3 & 2 \\ 4 & -11 & -4 & -5 \\ -13 & -6 & -11 & -6 \\ 4 & -5 & -4 & -11 \end{bmatrix}$$

Imaginary part:

$$\tilde{X}_{imag} = \begin{bmatrix} 0 & -5 & 0 & 5 \\ -9 & 8 & -7 & -4 \\ 0 & 13 & 0 & -13 \\ 9 & 4 & 7 & -8 \end{bmatrix}$$

Magnitude:

$$\tilde{X}_{magnitude} = \begin{bmatrix} 77 & 5.39 & 3 & 5.39 \\ 9.85 & 13.60 & 8.06 & 6.4 \\ 13 & 14.32 & 11 & 14.32 \\ 9.85 & 6.40 & 8.06 & 13.60 \end{bmatrix}$$

Phase:

$$\tilde{X}_{phase} = \begin{bmatrix} 0 & -1.19 & 0 & 1.19 \\ -1.15 & 2.51 & -2.09 & -2.47 \\ 3.14 & 2.00 & 3.14 & -2.00 \\ 1.15 & 2.47 & 2.09 & -2.51 \end{bmatrix}$$

➢ Computation of 2D-DFT: Example

- Compute the inverse 2D-DFT:

$$\mathrm{F}_4^*\tilde{\mathrm{X}}\mathrm{F}_4^* = \frac{1}{4^2}\begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & j & -1 & -j \\ 1 & -1 & 1 & -1 \\ 1 & -j & -1 & j \end{bmatrix}\begin{bmatrix} 77 & 2-5j & 3 & 2+5j \\ 4-9j & -11+8j & -4-7j & -5-4j \\ -13 & -6+13j & -11 & -6-13j \\ 4+9j & -5+4j & -4+7j & -11-8j \end{bmatrix}\begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & j & -1 & -j \\ 1 & -1 & 1 & -1 \\ 1 & -j & -1 & j \end{bmatrix}$$

$$= \frac{1}{4}\begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & j & -1 & -j \\ 1 & -1 & 1 & -1 \\ 1 & -j & -1 & j \end{bmatrix}\begin{bmatrix} 21 & 21 & 19 & 16 \\ -4-3j & -1-2j & 4-5j & 5+j \\ -9 & -7 & -3 & 6 \\ -4+3j & -1+2j & 4+5j & 5-j \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 3 & 6 & 8 \\ 9 & 8 & 8 & 2 \\ 5 & 4 & 2 & 3 \\ 6 & 6 & 3 & 3 \end{bmatrix} = \mathrm{X}$$

MATLAB function: *ifft2*

2D-DFT (Frequency) Domain Filtering

➢ Convolution Theorem

$f(x,y)$	$h(x,y)$	$g(x,y)$
input image	impulse response (filter)	output image

$$g(x,y) = f(x,y) \otimes h(x,y)$$

DFT ↓ ↑ IDFT DFT ↓ ↑ IDFT DFT ↓ ↑ IDFT

$$G(u,v) = F(u,v)\,H(u,v)$$

➢ Frequency Domain Filtering

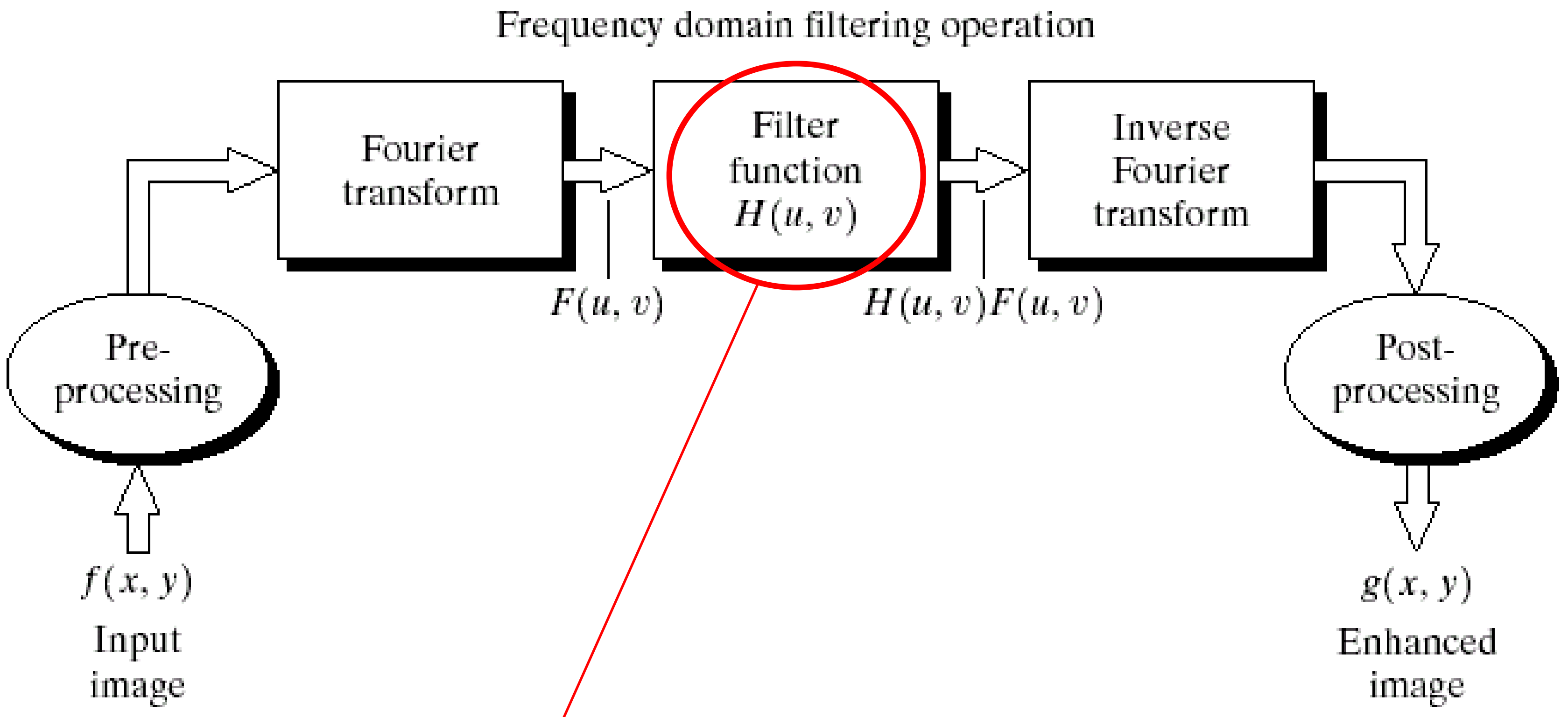


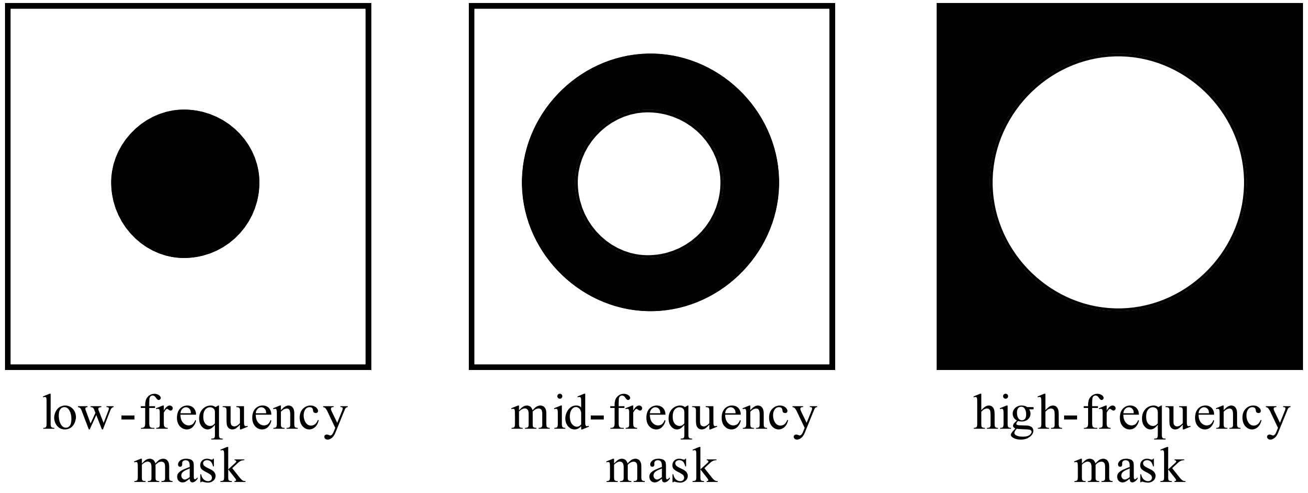
FIGURE 4.5 Basic steps for filtering in the frequency domain.

Filter design: design $H(u,v)$

From [Gonzalez & Woods]

➢ 2D-DFT Domain Filter Design

- Ideal lowpass, bandpass and highpass



➢ 2D-DFT Domain Filter Design

- Ideal lowpass, bandpass and highpass

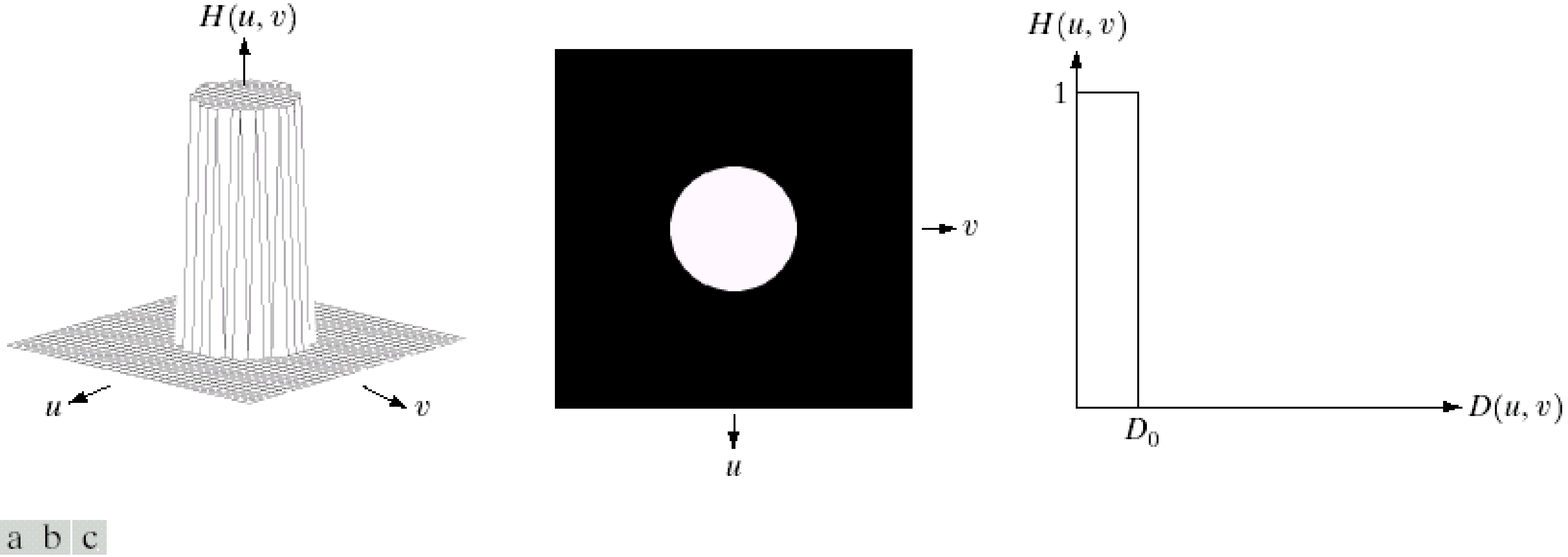
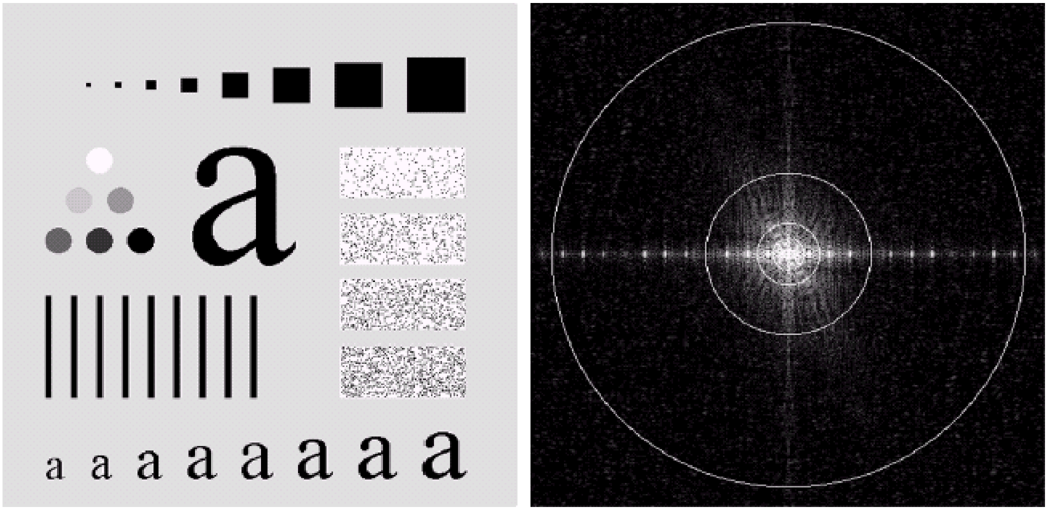


FIGURE 4.10 (a) Perspective plot of an ideal lowpass filter transfer function. (b) Filter displayed as an image. (c) Filter radial cross section.

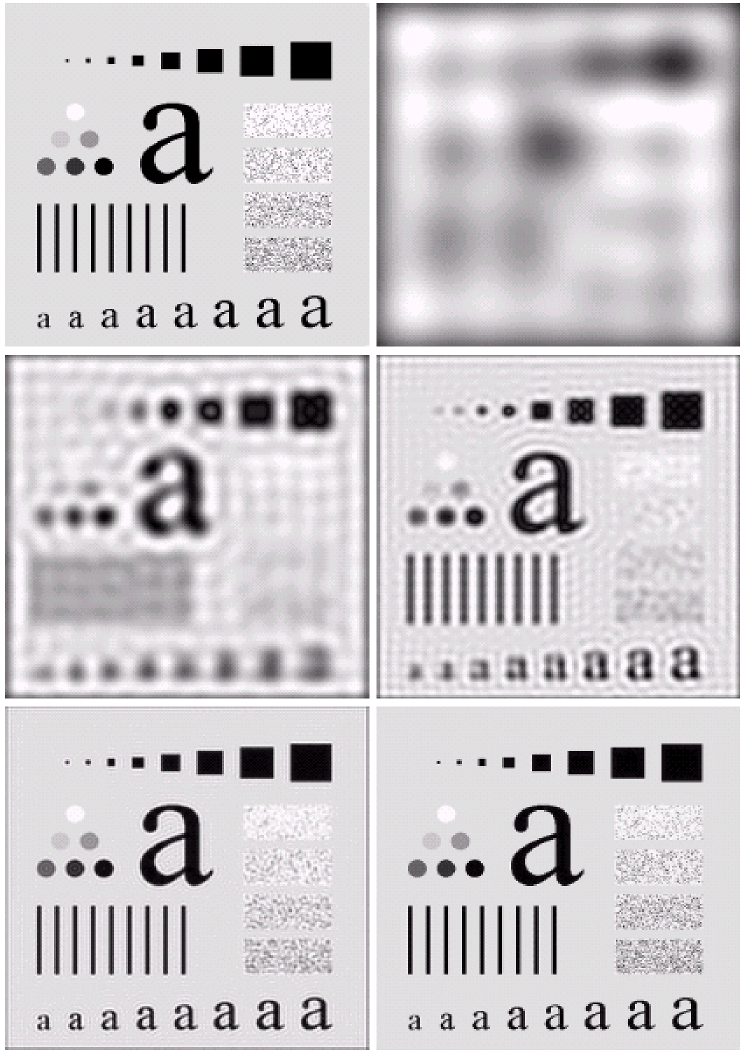
➢ 2D-DFT Domain Filter Design



a b

FIGURE 4.11 (a) An image of size 500 × 500 pixels and (b) its Fourier spectrum. The superimposed circles have radii values of 5, 15, 30, 80, and 230, which enclose 92.0, 94.6, 96.4, 98.0, and 99.5% of the image power, respectively.

Ideal lowpass filtering with cutoff frequencies set at radii values of 5, 15, 30, 80, and 230, respectively



From [Gonzalez & Woods]

➢ 2D-DFT Domain Filter Design

- Gaussian lowpass

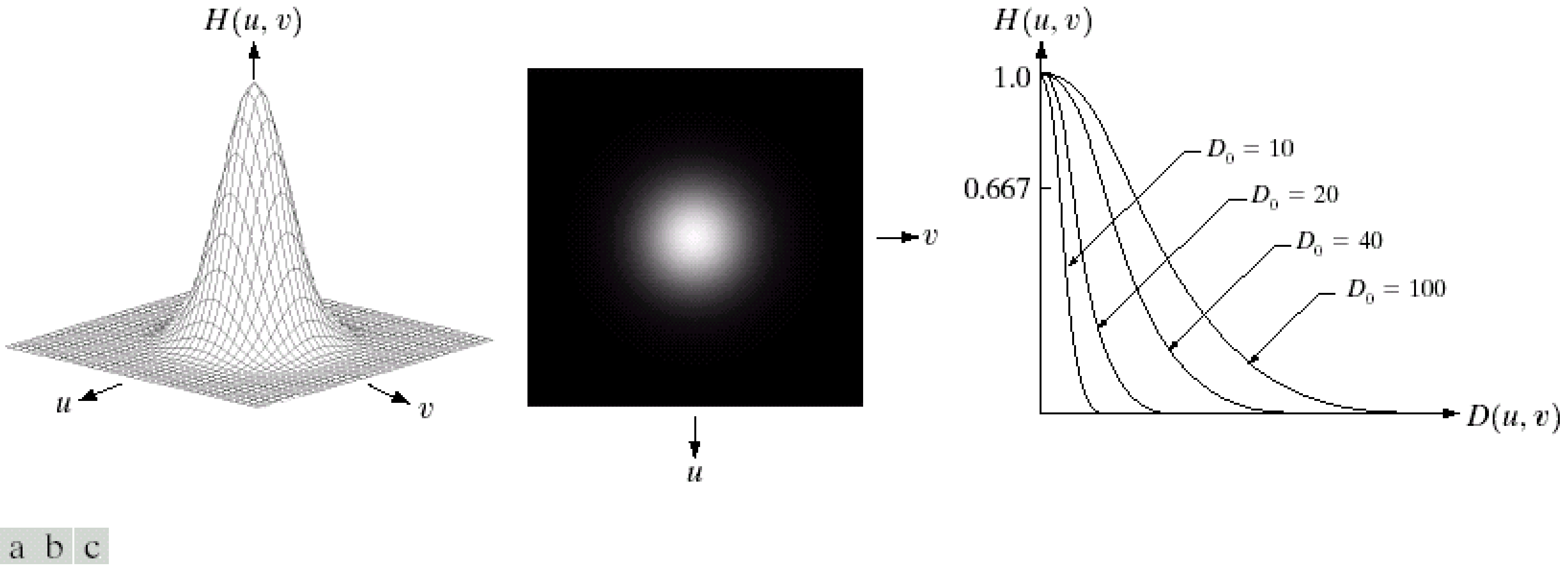
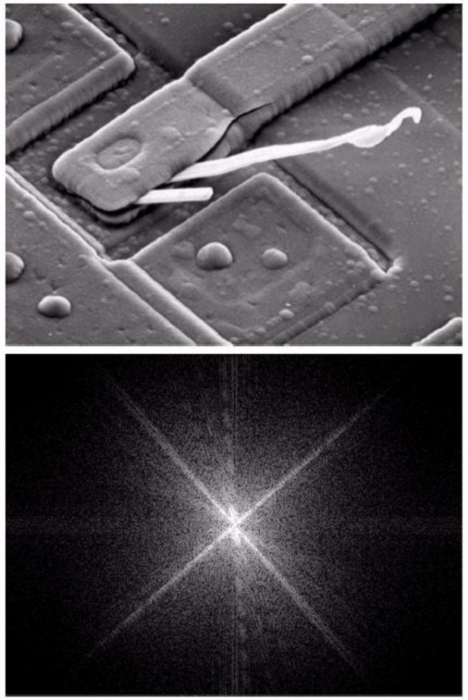


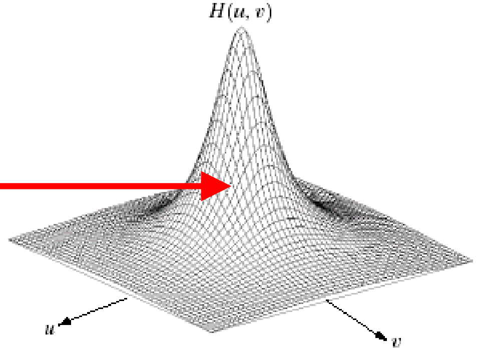
FIGURE 4.17 (a) Perspective plot of a GLPF transfer function. (b) Filter displayed as an image. (c) Filter radial cross sections for various values of D_0.

From [Gonzalez & Woods]

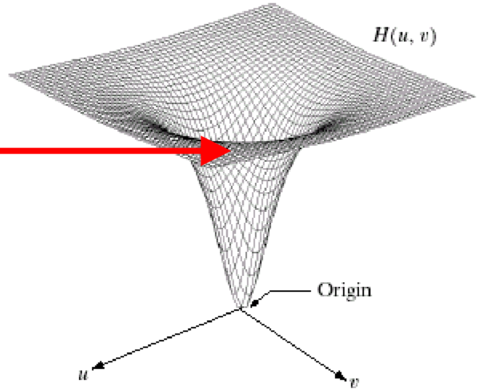
➢ 2D-DFT Domain Filter Design

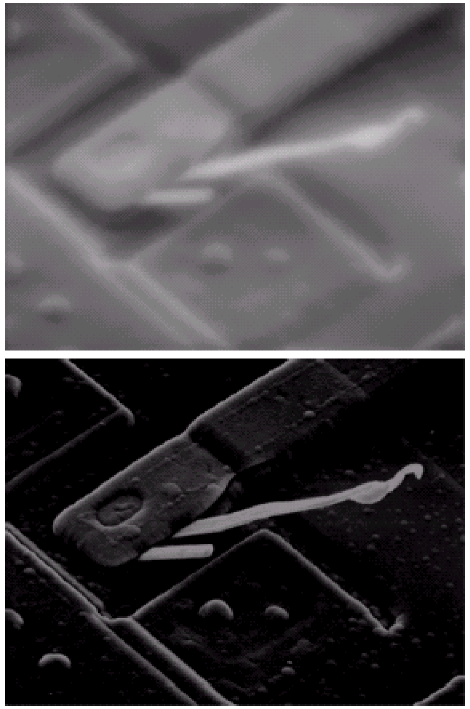


Gaussian lowpass filtering



Gaussian highpass filtering





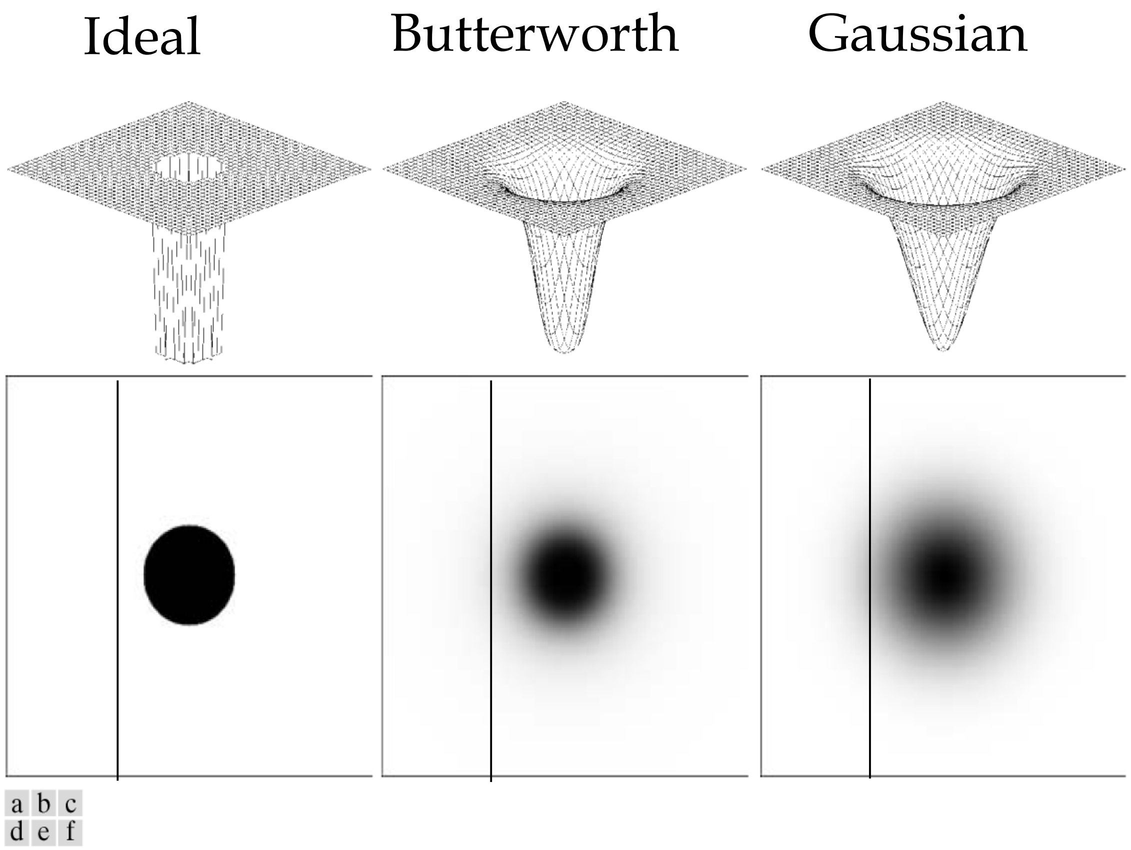
a b
c d

FIGURE 4.7 (a) A two-dimensional lowpass filter function. (b) Result of lowpass filtering the image in Fig. 4.4(a). (c) A two-dimensional highpass filter function. (d) Result of highpass filtering the image in Fig. 4.4(a).

From [Gonzalez & Woods]

➢ 2D-DFT Domain Filter Design

- Choices of highpass filters



From [Gonzalez & Woods]

FIGURE 4.17 Top row: Perspective plots of ideal, Butterworth, and Gaussian highpass filters. Bottom row: Corresponding images.

➢ 2D-DFT Domain Filter Design

Obtained by applying inverse 2D-DFT to the corresponding frequency domain filters

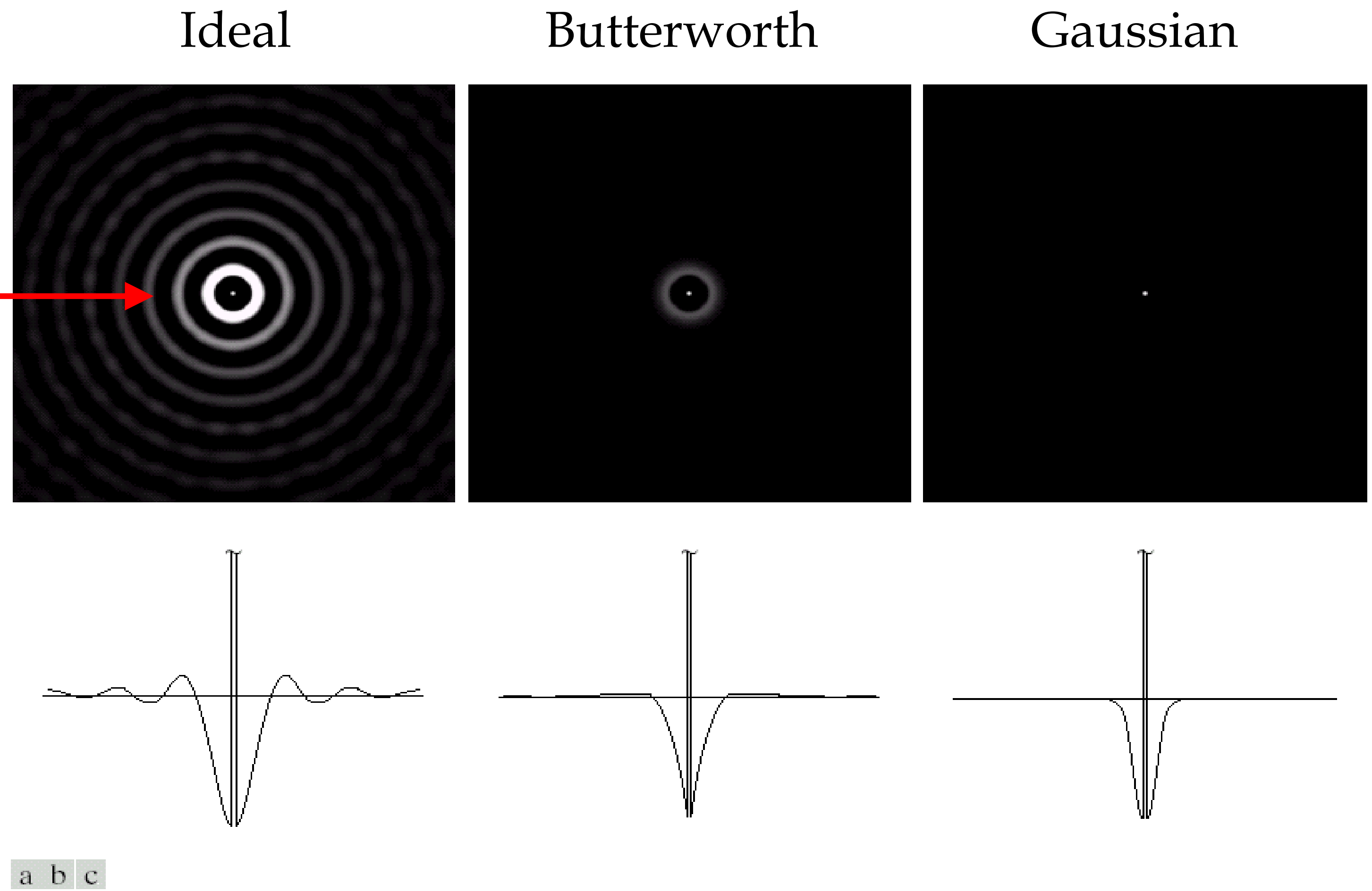


FIGURE 4.23 Spatial representations of typical (a) ideal, (b) Butterworth, and (c) Gaussian frequency domain highpass filters, and corresponding gray-level profiles.

From [Gonzalez & Woods]

➢ 2D-DFT Domain Filter Design

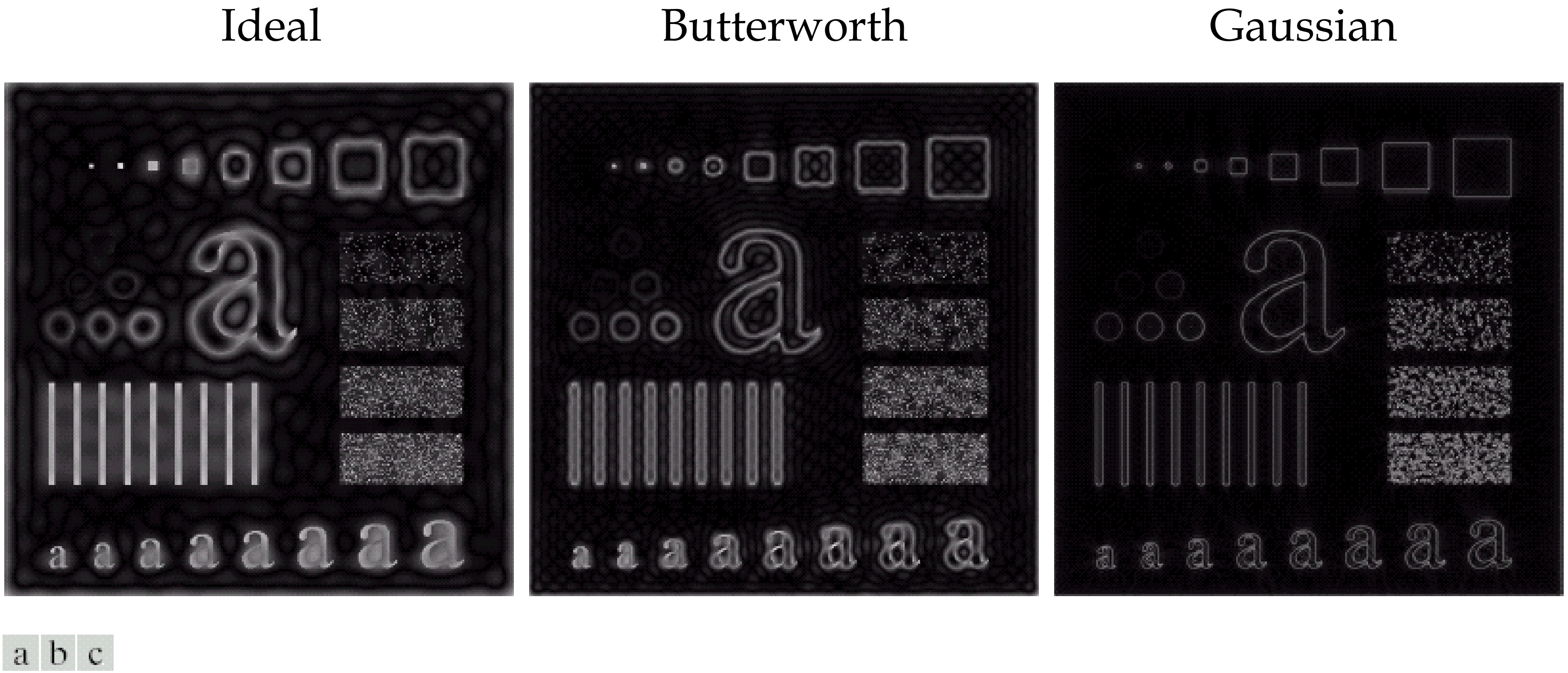
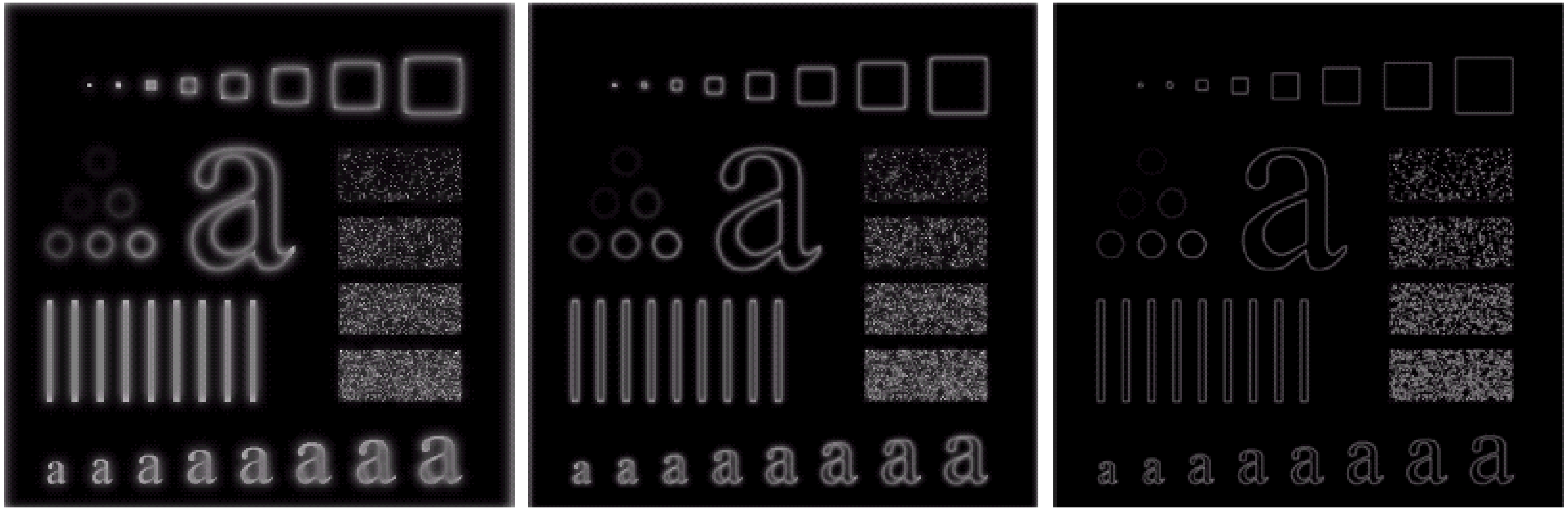


FIGURE 4.24 Results of ideal highpass filtering the image in Fig. 4.11(a) with $D_0 = 15$, 30, and 80, respectively. Problems with ringing are quite evident in (a) and (b).

From [Gonzalez & Woods]

➢ 2D-DFT Domain Filter Design

Gaussian filter with different width



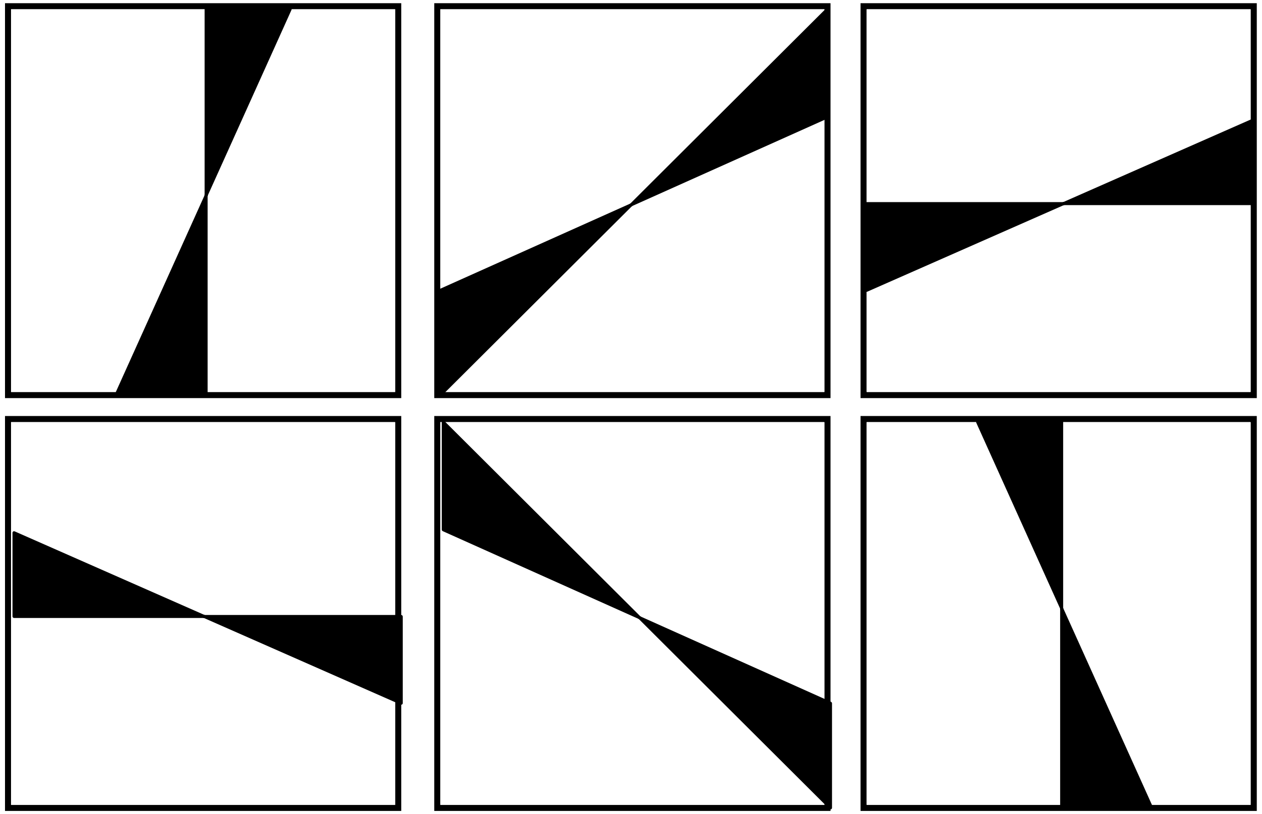
a b c

FIGURE 4.26 Results of highpass filtering the image of Fig. 4.11(a) using a GHPF of order 2 with $D_0 = 15$, 30, and 80, respectively. Compare with Figs. 4.24 and 4.25.

From [Gonzalez & Woods]

2D-DFT Domain Filter Design

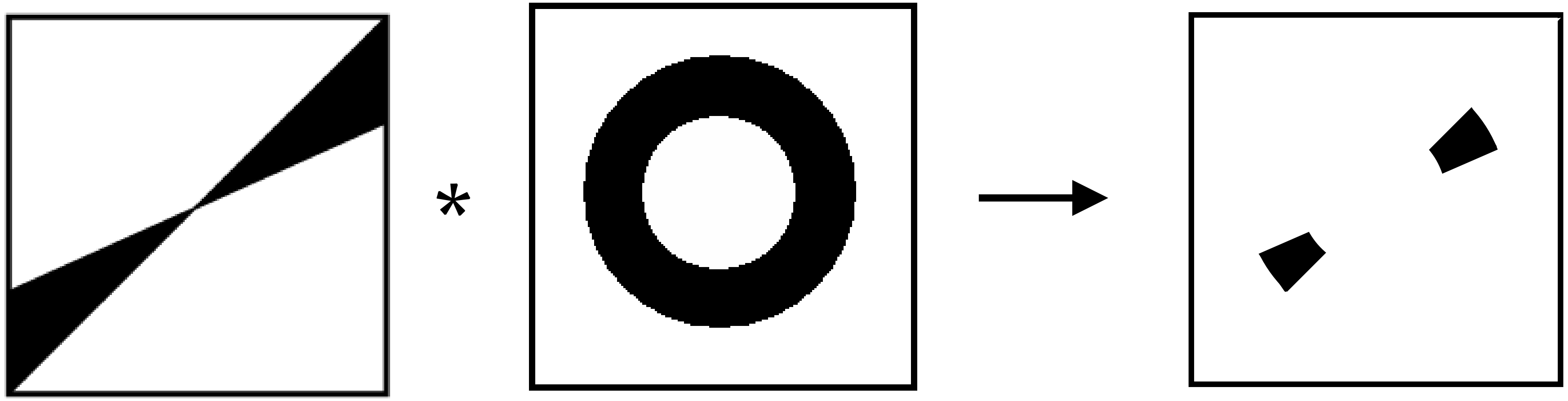
- Orientation selective filters



➢ 2D-DFT Domain Filter Design

- Narrowband Filtering

by combining radial and orientation selection



Dr/ Ayman Soliman


Thank you